Signetics

Linear Products

DESCRIPTION

The NE5037 is a low cost, complete successive-approximation analog-to-digital (A/D) converter, fabricated using Bipolar/I²L technology. With an external reference voltage, the NE5037 will accept input voltages between 0V and V_{REF}. An external START pulse of at least 300ns in duration will provide the 6-bit result of the conversion in parallel format. Full conversion with no missing codes occurs in 9 μ s.

FEATURES

- TTL-compatible inputs and outputs
- 3-State output buffer

NE5037 6-Bit A/D Converter (Parallel Outputs)

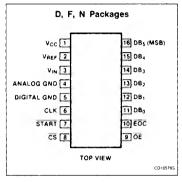
Product Specification

- Easy interface to CMOS microprocessors
- Fast conversion 9µs
- Guaranteed no missing codes over full temp range
- Single-supply operation, +5V
- Positive true binary outputs
- High-impedance analog inputs

APPLICATIONS

- Temperature control
- µP-based appliances
- Light level monitors
- Head position sensing
- Electronic toys
- Joystick interface

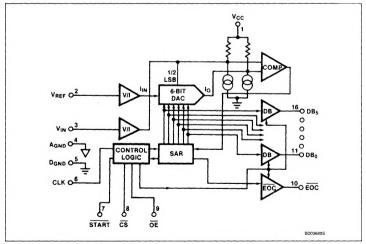
PIN CONFIGURATION



ORDERING INFORMATION

DESCRIPTION	TEMPERATURE RANGE	ORDER CODE
16-Pin Cerdip	0 to +70°C	NE5037F
16-Pin Plastic DIP	0 to +70°C	NE5037N
16-Pin Plastic SO package	0 to +70°C	NE5037D

BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

SYMBOL	YMBOL PARAMETER		UNIT	
V _{CC}	Power supply voltage	7	V	
VREF	Reference voltage 7			
VIN(Analog)	Analog input voltage 7			
VIN(Digital)	Digital input voltage (CS, OE, START, CLK)	7 -	V	
D _{OUT}	Data outputs (DB0 to DB5) 3-state mode Enabled mode (each output)	7 5	V mA	
ÊÔĈ	End of conversion	V _{CC}		
Δ_{GND}	Analog GND to digital GND	± 1	V	
T _A	Operating temperature range	0 to 70	°C	
T _{STG}	Storage temperature range	-65 to 150	°C	
TSOLD	Lead soldering temperature (10 seconds) 300			
PD	Maximum power dissipation, $T_A = 25^{\circ}C$ (still-air) ¹			
	F package	1190 1450	mW mW	
	N package D package	1450	mW	

NOTE:

1. Derate above 25°C at the following rates:

F package ≈ 9.5mW/°C. N package ≈ 11.6mW/°C.

D package = 8.7mW/°C.

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DC ELECTRICAL CHARACTERISTICS $V_{CC} = 5.0V$; $V_{REF} \approx 2.0V$; Clock = 1MHz; 0°C $\leq T_A \leq 70$ °C, unless otherwise specified. Typical values are specified at 25°C.

SYMBOL	PARAMETER			}		
		TEST CONDITIONS	Min	Тур	Max	UNIT
	Resolution Relative accuracy ^{1,2}		6	6 1⁄4	6 1⁄2	Bits LSB
V _{CC}	Positive supply voltage		+ 4.75	+ 5.0	+ 5.50	v
e _{FS} ezs	Full-scale gain error ^{2,3,4} Zero-scale offset error ²	$V_{REF} = 2.0V, T_A = 25^{\circ}C$ $V_{REF} = 2.0V, T_A = 25^{\circ}C$		± 1 ± ½	± 2 - ½, + 2	LSB LSB
PSR	Power supply rejection Max change in full-scale ²	$V_{REF} = 2.0V$ 4.75V $\leq V_{CC} \leq 5.5V$		± 1	LSB	
I _{IN} I _{REF} R _{IN}	Analog input bias current Reference bias current Analog input resistance	$\begin{array}{c} 0 \leqslant V_{\rm IN} \leqslant 2.5V \\ 0 \leqslant V_{\rm REF} \leqslant 2.5V \end{array}$	3	1 1 30	10 10	μΑ μΑ ΜΩ
VIH VIL IIH III IOH IOL IOZ ICC	Logic '1' input voltage Logic '0' input voltage Logic '1' input current Logic '0' input current Logic '1' output current ⁵ Logic '0' output current ⁵ 3-State leakage current Positive supply current	$2.4V \leq V_{OH}$ $V_{OL} \leq 0.4V$	2.0 300 1.6	1 ±0.1 18	0.8 10 10 ± 40 24	ν μΑ μΑ μΑ μΑ μΑ ΜΑ
PD	Power dissipation			1	132	mW

NOTES:

1. Relative accuracy is defined as the deviation of the code transition points from the ideal code transition points on a straight line drawn from zeroscale to full-scale of the device.

2. Specifications given in LSBs refer to the weight of the least significant bit at the 6-bit level which is 1.56% of the full-scale voltage.

3. Full-scale gain error is the deviation of the full-scale code transition point (111110 to 111111) from its ideal value.

4. The analog input voltage (V_{IN}) range is 0V to V_{REF} nominally, with the output remaining at 111111 even though the input may increase from V_{REF} to V_{CC} . (For optimum performance, V_{REF} can be any value from 1.5V to 2.5V.)

5. The data outputs have active pull-ups. The EOC line is open-collector with a nominal $5k\Omega$ internal pull-up resistor.

AC ELECTRICAL CHARACTERISTICS V_{CC} =5.0V; V_{REF} =2.0V; Clock=1MHz; 0°C \leq T_A \leq 70°C unless otherwise specified. Typical values are specified at 25°C. (Refer to AC test figures.)

SYMBOL	PARAMETER	то	FROM	TEST CONDITIONS	LIMITS			=
					Min	Тур	Max	UNIT
f _{MAX}	Maximum clock frequency				1			MHz
t _W	Start pulse width				300			ns
	Minimum positive/negative clock pulse width				300			ns
tCONV tP (OUT DATA) tP (OUT EOC) tP (3-STATE)	Conversion time Propagation delay ¹ Propagation delay ² Propagation delay, 3-State	Data out EOC 3-State Data	OE Clock OE	$ \begin{split} T_A &= 25^\circ\text{C}, \ t_R = t_F \leqslant 20\text{ns} \\ T_A &= 25^\circ\text{C}, \ t_R = t_F \leqslant 20\text{ns} \\ T_A &= 25^\circ\text{C}, \ t_R = t_F \leqslant 20\text{ns} \\ \end{split} $			9 500 800 500	Clock cycles ns ns ns

NOTES:

1. Propagation delay of data outputs is defined as the delay in the data outputs reading their final value after the low going edge of OE.

2. Propagation delay of EOC is defined as the delay in EOC going low, following the low going edge of the 9th clock pulse after the start pulse.

NE5037

6-Bit A/D Converter (Parallel Outputs)

CIRCUIT DESCRIPTION

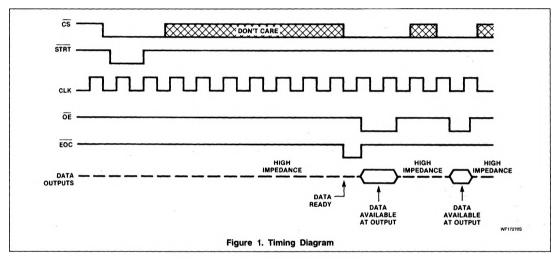
NE5037 is a complete 6-bit, parallel output, microprocessor compatible, A/D converter which incorporates the successive-approximation method. The chip includes the internal control logic, the successive-approximation register (SAR), 6-bit DAC, comparator and output buffers. An externally-generated clock source (max frequency = 1MHz) must be provided to Pin 6. An external reference voltage supplied to Pin 2 sets the full-scale range of the A/D converter.

The \overline{CS} pin must be at a low level prior to the start of the conversion process. Upon receipt

of a START pulse, the internal control logic resets the SAR. On the first low-going edge of the clock pulse, successive approximation conversion commences. Successive bits beginning with the MSB (D5) are supplied to the input of the internal 6-bit current output DAC by the I²L successive approximation register.

The comparator determines whether the output current of the DAC is greater or less than the input current, which is converted from the unknown analog input voltage through the V/I converter. If the DAC output is greater, that bit of the DAC is set to '0' and the corresponding output buffer goes to '0' simultaneously. If it is less, it stays at '1' and the output buffer also stays at '1'. On successive clock pulses, successive bits of the DAC are tried and the corresponding output buffer represents the bits of the DAC. On the eighth low-going edge of the clock pulse (after the receipt of the start pulse), the EOC pin goes low, thereby indicating that the conversion is complete. The output data is now valid. In order to access the result of the conversion, the OE pin must be set to a low level. EOC is reset to a high state when OE is low. When OE is in a '1' state, the output buffers are in a high impedance state.

Refer to Figure 1 for the timing diagram.



NE5037

6-Bit A/D Converter (Parallel Outputs)

TRANSFER CHARACTERISTICS

The ideal transfer characteristic of the NE5037 is shown in Figure 2.

The NE5037 is designed to have a nominal $\frac{1}{2}$ LSB offset so that the code transition points are located $\frac{1}{2}$ LSB on either side of the exact analog inputs for a given code.

Thus the first transition (000000 to 000001) will occur at an input of $\frac{1}{2}$ LSB (15.63mV with a V_{REF} of 2.0V). Subsequent transitions will occur at nominal increments of 1 LSB. The

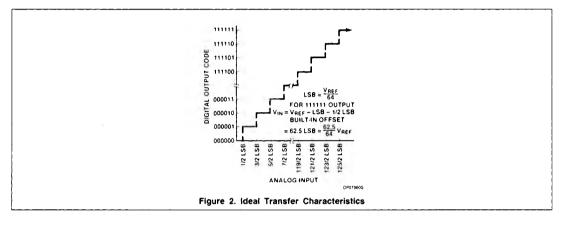
last transition (to full-scale — 111111) will occur at 62.5 LSB (1.953V at V_{REF} of 2.0V).

LAYOUT PRECAUTIONS

Analog ground (Pin 4) and digital ground (Pin 5) are not connected internally and should be connected together as close to the device as possible for optimum performance. The circuit will operate with as much as ± 200 mV between the two grounds but some degradation will occur. The leads to the analog inputs should be kept as short as possible to mini-

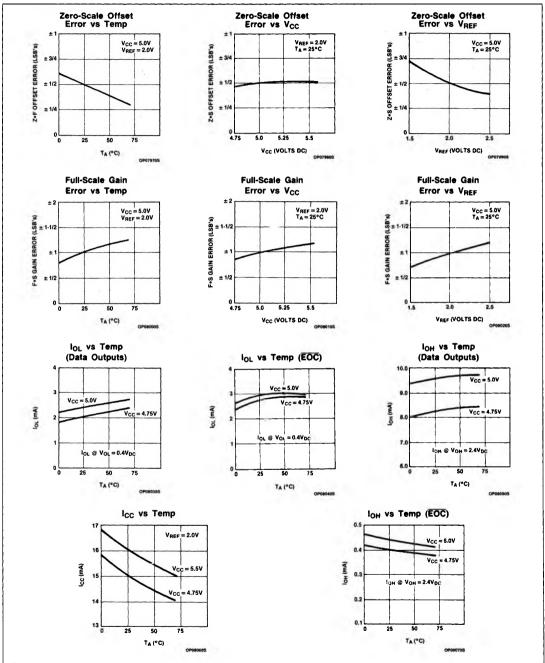
mize noise pick-up. Input bypass capacitors from the analog inputs to ground will eliminate noise pick-up. Power supplies should be decoupled with at least $1\,\mu\text{F}$ located close to the device to minimize the effects of noise spikes.

The reference input and the analog voltage input must both remain stable during conversion to insure accuracy and proper operation. This can be done by adequately bypassing these inputs and/or keeping the impedance of these inputs at or below $2k\Omega$.



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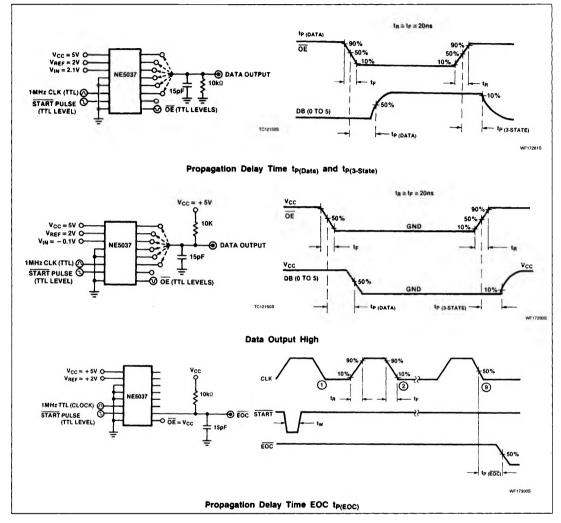
TYPICAL PERFORMANCE CHARACTERISTICS



NE5037

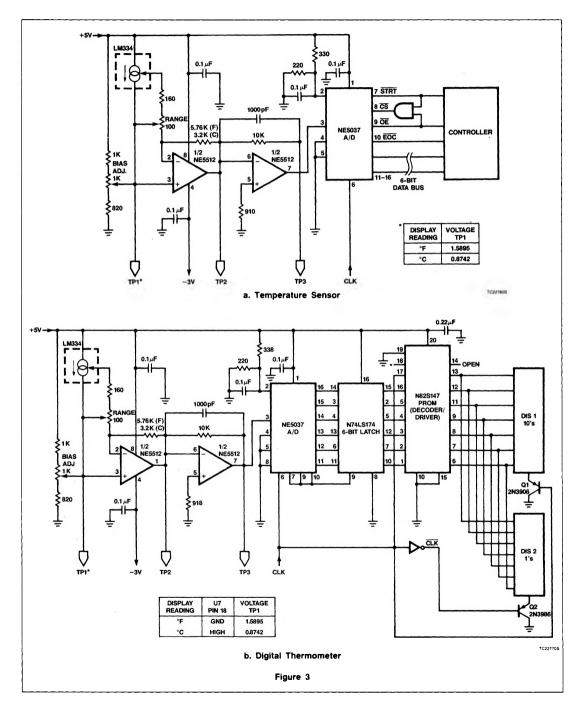
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AC TEST CIRCUITS AND WAVEFORMS



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NE5037



APPLICATION

• 0 to 63°C Temperature Sensor

CIRCUIT DESCRIPTION

The temperature sensor of Figure 3 provides an input to Pin 3 of the NE5037 of 32mV/°C. This 32mV is the value of one LSB for the NE5037. The LM334 is a three-terminal temperature sensor and provides a current of 1µA for each °Kelvin. The first section of the dual opmp is connected as a trans-impedance afplifier to convert the current from the LM334 to a voltage, which is amplified and inverted by the section amplifier. Note that the first amplifier requires different values of feedback resistance for °C and °F. The NE5512 was chosen for its low temperature coefficient of input bias current as excessive IOS tempco would degrade temperature trackina.

To read temperature, conversion is started by sending a momentary low signal to Pin 7 of the NE5037. When Pin 10 of the NE5037 goes low, conversion is complete and a low is applied to Pin 9 of the NE5037 to read data on Pins 11 through 16. Note that this temperature data is in straight binary format.

The controller can be a microprocessor in a temperature control application, or discrete circuitry in a simple temperature reporting application. A temperature reporting (digital thermometer) circuit is shown in Figure 3b. The NE5037 A/D converter is connected in a continuous conversion mode by connecting together Pins 7, 9, and 10. Should this pin be momentarily shorted to any relatively low impedance point, conversion will stop. Conversion will resume upon interruption and restoration of the power. These pins are also connected to the latch enable of a 6-bit latch because the data at the converter output is available for only a short time when the converter is in the continuous conversion mode. The (P)ROM) must have the correct code for converting the data from the NE5037 (used as address for the (P)ROMs) to the appropriate segment drive codes. Note that the circuit of Figure 3b shows a circuit which can be used to display either Fahrenheit or Centigrade temperatures.

The displayed output could easily be converted to degrees Fahrenheit (°F) by the controller of Figure 3a or through the (P)ROMs of Figure 3b. When doing this, a third (hundreds) digit (P)ROM and display will be needed for displaying temperatures above 99°F.

An inexpensive clock can be made from NAND gates or inverters, as shown in Figure 3c

CIRCUIT ADJUSTMENT

The circuit should be at a known ambient temperature for a few minutes before making adjustments.

- 1. Adjust bias adjust potentiometer for the voltage indicated in the chart in Figure 3b.
- With the circuit (or sensor U3, if it is remotely located) at a known temperature for 2 to 3 minutes, adjust range control for a correct reading on the displays.

This should provide an accuracy of ± 3 counts (3° F or C). Higher accuracy may require NE5037 reference voltage regulation.

