

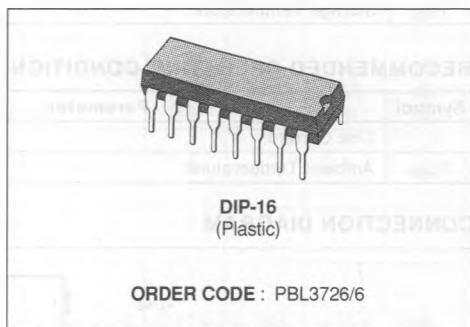
MASK - PROGRAMMABLE SPEECH CIRCUITS

SPEECH CIRCUIT

- MINIMUM NUMBER OF INEXPENSIVE EXTERNAL COMPONENTS, 6 CAPACITORS AND 10 RESISTORS
- MUTE FUNCTION FOR PARALLEL OPERATION WITH DTMF GENERATOR OR DECODING IMPULSING
- LOW VOLTAGE OPERATION, DOWN TO 3.3V
- VERY SHORT START-UP TIME
- CURRENT-SOURCE GENERATOR FOR ACTIVE MICROPHONES

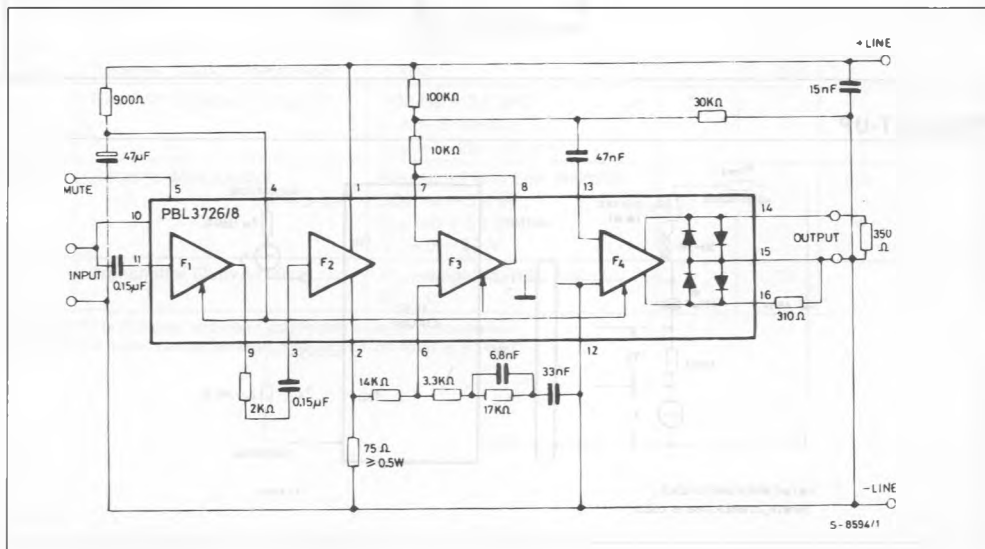
DESCRIPTION

PBL3726/8 is a standard version of the PBL3726 family of the mask-programmable, monolithic integrated speech circuits for use in electronic telephones. It is designed for use with a low impedance microphone. Sending and receiving gain is regulated with the line length. Different ranges of amplifier regulation for various current feeds can be obtained by mask programming. Typical current feeds such as 48V 2 x 800 , and 36V 2 x 500 can be handled.



Application-dependent parameters are line balance, sidetone level and frequency response are set by external components. Parameters are set independently which means easy adaptation for various market needs. An extra 20dB amplifier can be used for various purposes such as extra receiving gain with volume control or active sidetone balance.

TEST CIRCUIT



ABSOLUTE MAXIMUM RATINGS

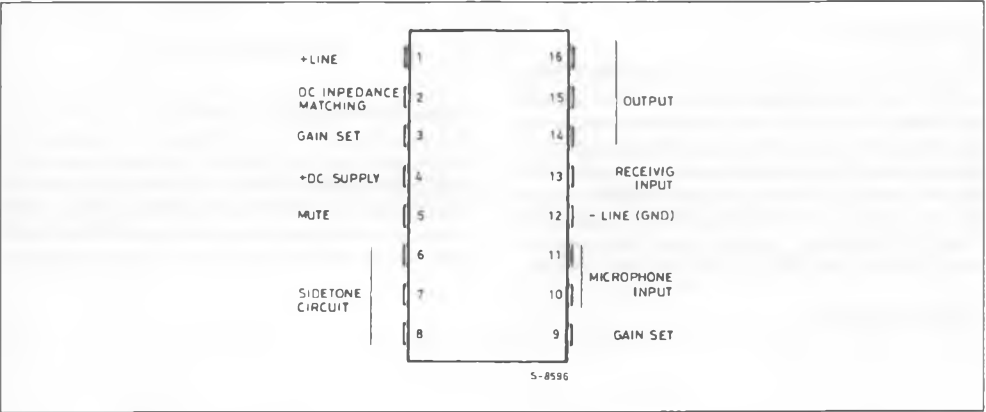
Maximum Ratings over Operating Free-air Temperature Range (unless otherwise stated)

Symbol	Parameter	Test Conditions	Unit
V_{DC}	Line Voltage, $t_p = 2\text{ s}$	22	V
I_{DC}	Continuous Operating Line Current	100	mA
T_J	Junction Temperature	150	°C
T_{amb}	Operating Ambient Temperature	- 40 to + 70	°C
T_{stg}	Storage Temperature	- 55 to + 150	°C

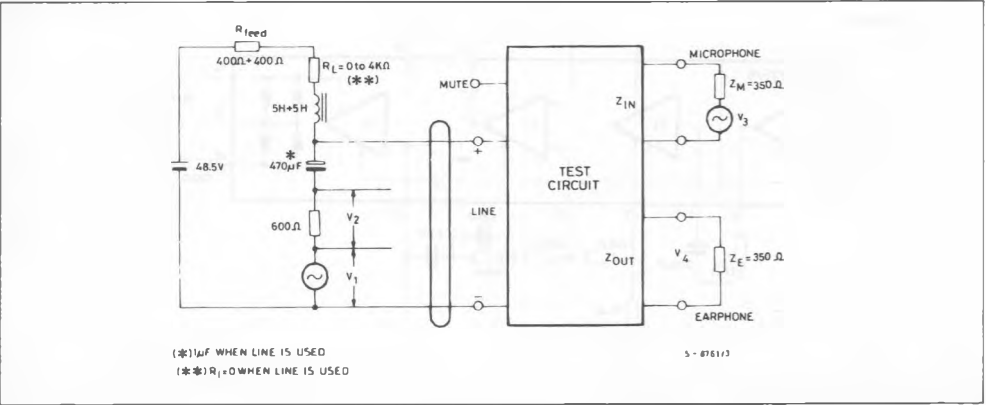
RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter	Min.	Typ.	Max.	Unit
I_L	Line Current	10		60	mA
T_{amb}	Ambient Temperature	- 15		45	°C

CONNECTION DIAGRAM



TEST SET-UP



THERMAL DATA

$R_{th\ j-amb}$	Thermal Resistance Junction-ambient	Max	80	°C/W
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ELECTRICAL CHARACTERISTICS (electrical characteristics over recommended operating conditions)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V_{DC}	Terminal Voltage	$I_{DC} = 10\text{ mA}$ $I_{DC} = 60\text{ mA}$	3.0 7	3.5 9	4.0 10.5	V V
G_T	Transmitting Gain *	$20 \cdot \log_{10} \left(\frac{V_2}{V_3} \right)$ 1 kHz $R_L = 0$ $E = E + 10\%$ $R_L = 400\ \Omega$ $R_L = 900\ \Omega - 2.2\text{ kHz}$	33 35.5 38	34 36.5 39	35 37.5 40	dB dB dB
REG_T	Transmitting Range of Regulation	1 kHz $R_L = 0\ \Omega$ $E = E + 10\%$ to $R_L = 900\ \Omega$	3	5	7	dB
Lin_T	Transmitting Frequency Response	200 Hz to 3.4 kHz	- 1		1	dB
G_R	Receiving Gain (*)	$20 \cdot \log_{10} \left(\frac{V_4}{V_1} \right)$ 1 kHz $R_L = 0\ \Omega$ $E = E + 10\%$	- 17.9	- 16.5	- 15.1	dB
REG_R	Receiving Range of Regulation	1 kHz $R_L = 0\ \Omega$ $E = E + 10\%$ to $R_L = 900\ \Omega$	3	5	7	dB
Lin_R	Receiving Frequency Response	200 Hz to 3.4 kHz	- 1		1	dB
Z_{IN}	Transmitter Input Impedance	1 kHz	17	20		k Ω
V_T	Transmitter Dynamic Output	200 Hz - 3.4 kHz $\leq 2\%$ Distortion $I_{DC} = 11.25 - 50\text{ mA}$	1.1			V _p
V_T	Transmitter Max Output	200 Hz - 3.4 kHz $I_{DC} = 0 - 50\text{ mA}$ $V_3 = 0 - 1\text{ V}$			3	V _p
Z_{OUT}	Receiver Output Impedance	1 kHz		3 + 310		Ω
V_R	Receiver Dynamic Output **	200 Hz - 3.4 kHz $\leq 3\%$ Distortion $I_{DC} = 11.25 - 50\text{ mA}$	0.4			V _p
V_R	Receiver Max Output	Measured with Line Rectifier 200 Hz - 3.4 kHz $I_{DC} = 0 - 50\text{ mA}$ $V_1 = 0 - 50\text{ V}$			0.9	V _p
N_T	Transmitter Output Noise	$P_{50\mu s}$ -weighted, REL 1 V $R_L = 0$		- 75		

* Adjustable to both higher and lower values with external components.

** The dynamic output can be doubled. See application notes at R14.

ELECTRICAL CHARACTERISTICS (continued)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
N_R	Receiver Output Noise	A-weighted, REL 1 V, with Cable 0.5 Km \varnothing 0.5 mm ; 0.3 Km \varnothing 0.4 mm		- 85		dB _A
I_M	Mute Input Current		0.1			mA
V_{DC}	Minimum DC-line Voltage when Muted	$I_{DC} = 2.5$ mA $I_M = 0.1$ mA	3.0			V
I_S	Supply Current for Microphone Amplifier	$I_{DC} = 11.25 - 50$ mA	300			μ A
I_{DC}	DC Voltage for Microphone Amplifier	$I_{DC} = 11.25 - 50$ mA			2	V

* Adjustable to both higher and lower values with external components.

** The dynamic output can be doubled. See application notes at R14.

Figure 1 : Typical Application.

